

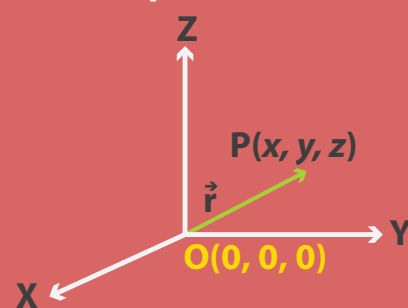
# Vector Algebra - Part I

**Vector** It is a quantity which has both magnitude and direction.

## Position Vector

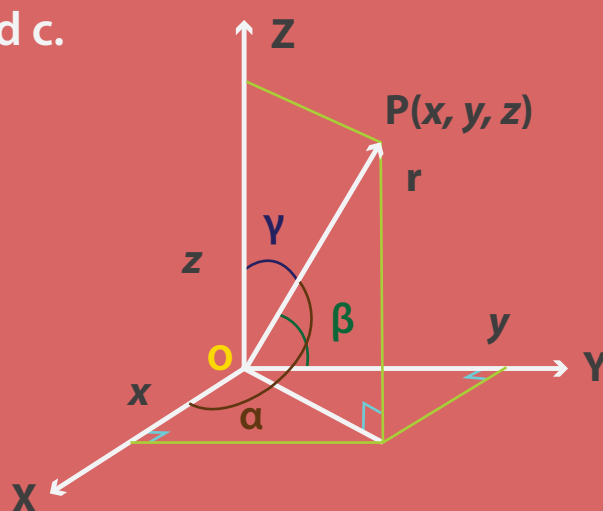
For a point  $P(x, y, z)$  in 3-D coordinate system,  $\overline{OP}$  or  $\vec{r}$  is the position vector with origin  $O$  as initial point.

Magnitude of  $\overline{OP} = |\overline{OP}| = \sqrt{x^2 + y^2 + z^2}$



## Direction Cosines and Direction Ratios

- 1 Position vector  $\overline{OP}$  makes angle  $\alpha$ ,  $\beta$  and  $\gamma$  with  $x$ ,  $y$  and  $z$  axes.
- 2  $\cos \alpha$ ,  $\cos \beta$  and  $\cos \gamma$  are the direction cosine of vector  $\overline{OP}$  and denoted by  $l$ ,  $m$  and  $n$ .
- 3 Direction cosines are unique for a given line
- 4 Number proportional to direction cosines are called as direction ratios, denoted by  $a$ ,  $b$  and  $c$ .



- 5 We also have  $l^2 + m^2 + n^2 = 1$ .

## Types Of Vectors

- 1 **Zero Vector** Vector with zero magnitude, denoted as  $\vec{0}$
- 2 **Unit Vector** Vector whose magnitude is 1 unit. Unit vector along  $\vec{a}$  is denoted as  $\hat{a}$
- 3 **Cointial Vectors** Two or more vectors with same initial point
- 4 **Collinear Vectors** Two or more vectors lying on the same or parallel lines.
- 5 **Equal Vectors** Two or more vectors with same magnitude and direction.
- 6 **Negative Vectors** Vector with same magnitude but opposite direction as that of the given vector.

## Addition Of Vectors

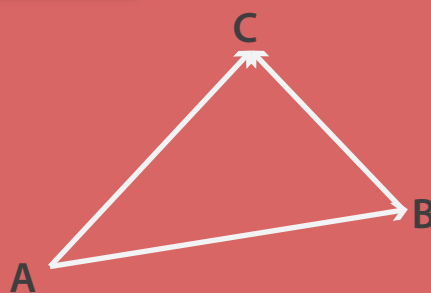
### Triangle Law Of Addition

$$\overline{AC} = \overline{AB} + \overline{BC}$$

$$\text{i.e } \overline{AB} + \overline{BC} - \overline{AC} = 0$$

$$\overline{AB} + \overline{BC} + \overline{CA} = 0$$

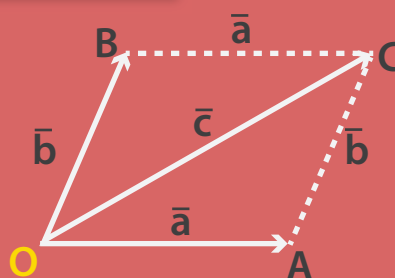
$$\overline{AB} + \overline{BC} + \overline{CA} = \overline{AA}$$



### Parallelogram Law Of Addition

$$\overline{OA} + \overline{OB} = \overline{OC}$$

$$\text{i.e } \vec{a} + \vec{b} = \vec{c}$$



### Properties Of Vector Addition

- $\vec{a} + \vec{b} = \vec{b} + \vec{a}$  ; commutative property  
 $(\vec{a} + \vec{b}) + \vec{c} = \vec{a} + (\vec{b} + \vec{c})$  ; Associative property

## Multiplication Of Scalar and Vector

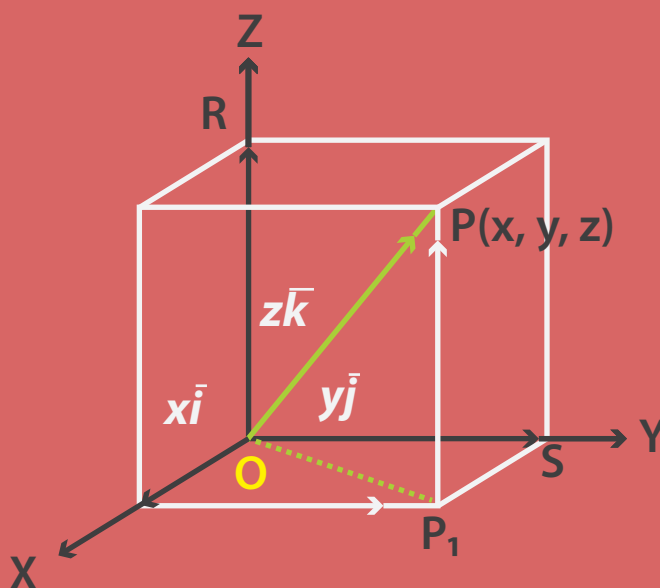
- 1 Multiplication of scalar  $\lambda$  with vector  $\vec{a}$  is  $\lambda\vec{a}$ .
- 2  $\lambda\vec{a}$  is collinear to vector  $\vec{a}$ .
- 3 Direction of  $\lambda\vec{a}$  depends upon  $\lambda$ .
  - a If  $\lambda$  is positive its direction is same as that of  $\vec{a}$ .
  - b If  $\lambda$  is negative its direction is opposite to that of  $\vec{a}$ .
- 4 Magnitude of  $\lambda\vec{a} = |\lambda\vec{a}| = |\lambda||\vec{a}|$

## Components Of Vectors

For position vector  $\vec{OP}$  of a point  $P(x, y, z)$ , We have

$$\vec{OP} = x\vec{i} + y\vec{j} + z\vec{k}$$

Where  $\vec{i}, \vec{j}$  and  $\vec{k}$  are unit vectors along  $x, y$  and  $z$  - axes , and



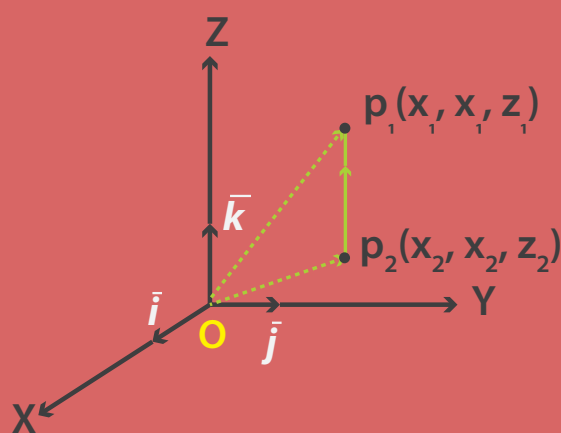
$x\vec{i}, y\vec{j}$  and  $z\vec{k}$  are the components of vector  $\vec{OP}$  along  $x, y$  and  $z$  - axes.

## Vector Joining Two Points

$$p_1(x_1, y_1, z_1) \quad p_2(x_2, y_2, z_2)$$

$$\vec{p_1p_2} = (x_2 - x_1)\vec{i} + (y_2 - y_1)\vec{j} + (z_2 - z_1)\vec{k}$$

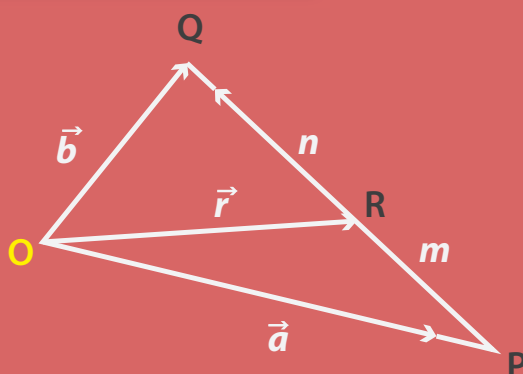
$$|\vec{p_1p_2}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$



## Section Formula

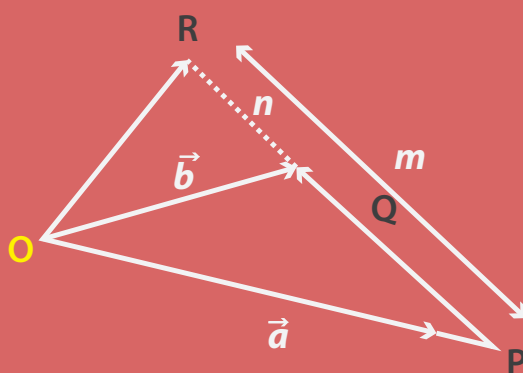
### Internal Division

$$\vec{r} = \frac{m\vec{b} + n\vec{a}}{m + n}$$



### External Division

$$\vec{r} = \frac{m\vec{b} - n\vec{a}}{m - n}$$



### Midpoint Formula

$$\vec{r} = \frac{\vec{a} + \vec{b}}{2}$$

## Scalar Product

For vectors  $\vec{a}$  and  $\vec{b}$ . It is denoted as

$$\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$$

Where  $\theta$  is angle between  $a$  and  $b$ ,  $0 \leq \theta \leq \pi$

### Properties Of Scalar Product

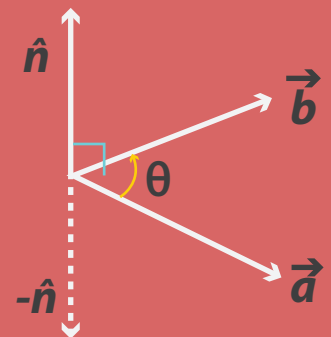
- 1  $\vec{a} \cdot \vec{b}$  is a scalar quantity.
- 2  $\vec{a} \cdot \vec{b} = 0 \Leftrightarrow \vec{a} \perp \vec{b}$
- 3  $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \Leftrightarrow \theta = 0^\circ$
- 4  $\vec{a} \cdot \vec{b} = -|\vec{a}| |\vec{b}| \Leftrightarrow \theta = 180^\circ$
- 5  $\vec{i} \cdot \vec{i} = \vec{j} \cdot \vec{j} = \vec{k} \cdot \vec{k} = 1$
- 6  $\vec{i} \cdot \vec{j} = \vec{j} \cdot \vec{k} = \vec{k} \cdot \vec{i} = 0$
- 7  $\cos \theta = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|}$
- 8  $\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$
- 9  $\vec{a} \cdot (\vec{b} + \vec{c}) = \vec{a} \cdot \vec{b} + \vec{a} \cdot \vec{c}$
- 10 if  $\vec{a} = a_1\vec{i} + a_2\vec{j} + a_3\vec{k}$  and  $\vec{b} = b_1\vec{i} + b_2\vec{j} + b_3\vec{k}$  then  $\vec{a} \cdot \vec{b} = a_1b_1 + a_2b_2 + a_3b_3$
- 11  $(\lambda\vec{a}) \cdot \vec{b} = \lambda(\vec{a} \cdot \vec{b}) = \vec{a} \cdot (\lambda\vec{b})$

## Vector Product

For vectors  $\vec{a}$  and  $\vec{b}$  it is defined as

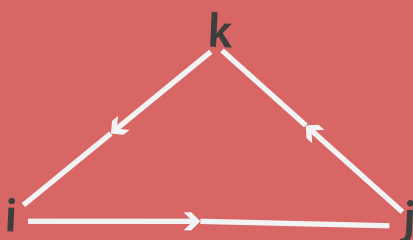
$$\vec{a} \times \vec{b} = |\vec{a}| |\vec{b}| \sin \theta \hat{n}$$

Where  $\theta$  is an angle between  $\vec{a}$  and  $\vec{b}$ ,  $0 \leq \theta \leq \pi$  and  $\hat{n}$  is the unit vector perpendicular to both  $\vec{a}$  and  $\vec{b}$  such that  $\vec{a}$ ,  $\vec{b}$  and  $\hat{n}$  form a right handed system



### Properties Of Vector Product

- 1  $\vec{a} \times \vec{b}$  is a vector.
- 2  $\vec{a} \times \vec{b} = 0 \Leftrightarrow \vec{a} \parallel \vec{b}$
- 3  $\vec{i} \times \vec{i} = \vec{j} \times \vec{j} = \vec{k} \times \vec{k} = 0$
- 4  $\vec{i} \times \vec{j} = \vec{j} \times \vec{k} = \vec{i}$ ,  $\vec{k} \times \vec{i} = \vec{j}$
- 5  $\sin \theta = \frac{|\vec{a} \times \vec{b}|}{|\vec{a}| |\vec{b}|}$
- 6  $\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$
- 7  $\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$
- 8  $\lambda(\vec{a} \times \vec{b}) = (\lambda\vec{a}) \times \vec{b} = \vec{a} \times (\lambda\vec{b})$
- 9 if  $\vec{a} = a_1\vec{i} + a_2\vec{j} + a_3\vec{k}$  and  $\vec{b} = b_1\vec{i} + b_2\vec{j} + b_3\vec{k}$  then



$$\vec{a} \times \vec{b} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$